Preflows

Definition 1 An (s, t)-preflow is a function $f : E \mapsto \mathbb{R}^+$ that satisfies 1. For each edge e $0 \le f(e) \le c(e)$. (capacity constraints) 2. For each $v \in V \setminus \{s, t\}$ $\sum_{e \in out(v)} f(e) \le \sum_{e \in into(v)} f(e)$.

Preflows

Definition:

A labelling is a function $\ell: V \to \mathbb{N}$. It is valid for preflow f if

- ℓ(u) ≤ ℓ(v) + 1 for all edges (u, v) in the residual graph G_f (only non-zero capacity edges!!!)
- ▶ $\ell(s) = n$
- $\blacktriangleright \ell(t) = 0$

Intuition:

The labelling can be viewed as a height function. Whenever the height from node u to node v decreases by more than 1 (i.e., it goes very steep downhill from u to v), the corresponding edge must be saturated.

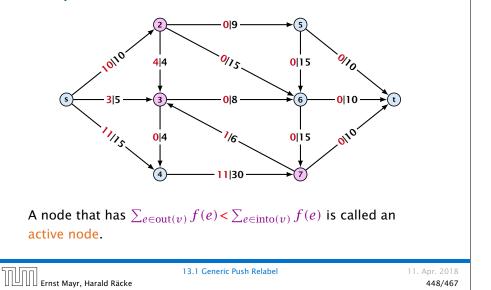
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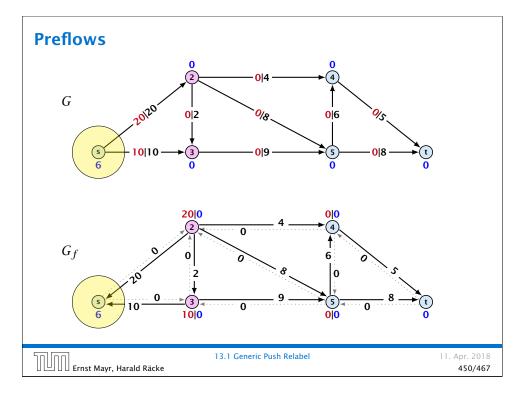
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Preflows

Example 2





Preflows

Lemma 3

A preflow that has a valid labelling saturates a cut.

Proof:

- There are n nodes but n + 1 different labels from $0, \ldots, n$.
- ► There must exist a label d ∈ {0,..., n} such that none of the nodes carries this label.
- Let $A = \{v \in V \mid \ell(v) > d\}$ and $B = \{v \in V \mid \ell(v) < d\}$.
- We have s ∈ A and t ∈ B and there is no edge from A to B in the residual graph G_f; this means that (A, B) is a saturated cut.

Lemma 4

A flow that has a valid labelling is a maximum flow.

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Changing a Preflow

An arc (u, v) with $c_f(u, v) > 0$ in the residual graph is admissible if $\ell(u) = \ell(v) + 1$ (i.e., it goes downwards w.r.t. labelling ℓ).

The push operation

Consider an active node u with excess flow $f(u) = \sum_{e \in into(u)} f(e) - \sum_{e \in out(u)} f(e)$ and suppose e = (u, v)is an admissible arc with residual capacity $c_f(e)$.

We can send flow $\min\{c_f(e), f(u)\}$ along e and obtain a new preflow. The old labelling is still valid (!!!).

- saturating push: min{f(u), c_f(e)} = c_f(e) the arc e is deleted from the residual graph
- non-saturating push: min{f(u), c_f(e)} = f(u) the node u becomes inactive

Note that a push-operation may be saturating **and** non-saturating at the same time.

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Push Relabel Algorithms

Idea:

- start with some preflow and some valid labelling
- successively change the preflow while maintaining a valid labelling
- stop when you have a flow (i.e., no more active nodes)

Note that this is somewhat dual to an augmenting path algorithm. The former maintains the property that it has a feasible flow. It successively changes this flow until it saturates some cut in which case we conclude that the flow is maximum. A preflow push algorithm maintains the property that it has a saturated cut. The preflow is changed iteratively until it fulfills conservation constraints in which case we can conclude that we have a maximum flow.

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Push Relabel Algorithms

The relabel operation

Consider an active node u that does not have an outgoing admissible arc.

Increasing the label of u by 1 results in a valid labelling.

- Edges (w, u) incoming to u still fulfill their constraint $\ell(w) \le \ell(u) + 1$.
- An outgoing edge (u, w) had ℓ(u) < ℓ(w) + 1 before since it was not admissible. Now: ℓ(u) ≤ ℓ(w) + 1.

Push Relabel Algorithms

Intuition:

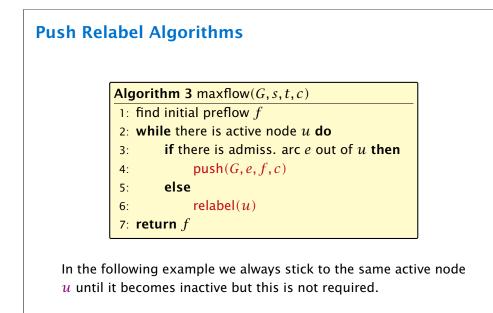
We want to send flow downwards, since the source has a height/label of n and the target a height/label of 0. If we see an active node u with an admissible arc we push the flow at u towards the other end-point that has a lower height/label. If we do not have an admissible arc but excess flow into u it should roughly mean that the level/height/label of u should rise. (If we consider the flow to be water then this would be natural.)

Note that the above intuition is very incorrect as the labels are integral, i.e., they cannot really be seen as the height of a node.

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13.1 Generic Push Relabel

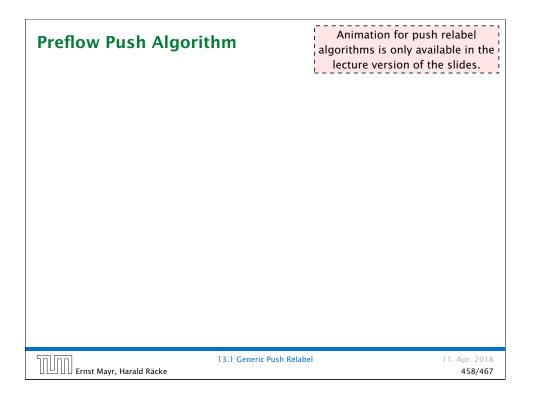
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Reminder

- In a preflow nodes may not fulfill conservation constraints; a node may have more incoming flow than outgoing flow.
- Such a node is called active.
- A labelling is valid if for every edge (u, v) in the residual graph $\ell(u) \leq \ell(v) + 1$.
- An arc (u, v) in residual graph is admissible if $\ell(u) = \ell(v) + 1$.
- A saturating push along *e* pushes an amount of *c*(*e*) flow along the edge, thereby saturating the edge (and making it dissappear from the residual graph).
- A non-saturating push along e = (u, v) pushes a flow of f(u), where f(u) is the excess flow of u. This makes u inactive.

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50 60	13.1 Generic Push Relabel	Hence, the ex	xcess
► Let <i>f</i> (<i>B</i>)	= $\sum_{v \in B} f(v)$ be the excess flow of all nodes in		
	sidual graph there are no edges into A , and, here leaving A /entering B can carry any flow.	since, ≤ 0	
In the following we show that a node b ∈ B ha f(b) = 0 which gives the lemma.		flow $= \sum_{b \in B} \left(\begin{array}{c} \\ u \end{array} \right)$	$\sum_{\nu \in A} f(\iota$
	note the set of nodes that can reach s , and let E he remaining nodes. Note that $s \in A$.	$b \in B \setminus u$	$\sum_{v \in V} f(v)$
Proof.		$f(B) = \sum_{b \in B} f(A)$	<i>b</i>)
An active node has a path to s in the residual graph.			
Lemma 5		We have	
Analysis	Note that the lemma is almost trivial. A node v has flow means that the current preflow ships something residual graph allows to <i>undo</i> flow. Therefore, the ist a path that can undo the shipment and move it However, a formal proof is required.	and to v . The function $Let f : E \to \mathbb{R}$	${ m R}^+_0$ be a $f(s)$

Analysis

Lemma 6

The label of a node cannot become larger than 2n - 1.

Proof.

▶ When increasing the label at a node *u* there exists a path from *u* to *s* of length at most *n* − 1. Along each edge of the path the height/label can at most drop by 1, and the label of the source is *n*.

Lemma 7

There are only $\mathcal{O}(n^2)$ relabel operations.

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Let $f : E \to \mathbb{R}_0^+$ be a preflow. We introduce the notation

$$f(x, y) = \begin{cases} 0 & (x, y) \notin E \\ f((x, y)) & (x, y) \in E \end{cases}$$

$$(B) = \sum_{b \in B} f(b)$$

= $\sum_{b \in B} \left(\sum_{v \in V} f(v, b) - \sum_{v \in V} f(b, v) \right)$
= $\sum_{b \in B} \left(\sum_{v \in A} f(v, b) + \sum_{v \in B} f(v, b) - \sum_{v \in A} f(b, v) - \sum_{v \in B} f(b, v) \right)$
= $-\sum_{b \in B} \sum_{v \in A} f(b, v)$
 ≤ 0

Hence, the excess flow f(b) must be 0 for every node $b \in B$.

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Analysis

Lemma 8

The number of saturating pushes performed is at most $\mathcal{O}(mn)$.

Proof.

- Suppose that we just made a saturating push along (u, v).
- Hence, the edge (u, v) is deleted from the residual graph.
- For the edge to appear again, a push from v to u is required.
- Currently, $\ell(u) = \ell(v) + 1$, as we only make pushes along admissible edges.
- For a push from v to u the edge (v, u) must become admissible. The label of v must increase by at least 2.
- Since the label of v is at most 2n − 1, there are at most n pushes along (u, v).

Lemma 9

The number of non-saturating pushes performed is at most $O(n^2m)$.

Proof.

- Define a potential function $\Phi(f) = \sum_{\text{active nodes}\nu} \ell(\nu)$
- A saturating push increases Φ by ≤ 2n (when the target node becomes active it may contribute at most 2n to the sum).
- A relabel increases Φ by at most 1.
- ► Hence,

#non-saturating_pushes \leq #relabels + $2n \cdot$ #saturating_pushes $\leq O(n^2m)$.

Analysis

Proof:

For every node maintain a list of admissible edges starting at that node. Further maintain a list of active nodes.

A push along an edge (u, v) can be performed in constant time

- check whether edge (v, u) needs to be added to G_f
- check whether (u, v) needs to be deleted (saturating push)
- check whether u becomes inactive and has to be deleted from the set of active nodes

A relabel at a node u can be performed in time O(n)

- check for all outgoing edges if they become admissible
- check for all incoming edges if they become non-admissible

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Analysis

Theorem 10

There is an implementation of the generic push relabel algorithm with running time $O(n^2m)$.

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Analysis

For special variants of push relabel algorithms we organize the neighbours of a node into a linked list (possible neighbours in the residual graph G_f). Then we use the discharge-operation:

Algorithm 4 discharge(*u*) 1: while *u* is active do

- 2: $v \leftarrow u.current-neighbour$
- 3: if v =null then
- 4: relabel(u)
 - u.current-neighbour ← u.neighbour-list-head
- 6: **else**

5:

7:

- if (u, v) admissible then push(u, v)
- 8: **else** *u.current-neighbour* \leftarrow *v.next-in-list*

Note that *u.current-neighbour* is a global variable. It is only changed within the discharge routine, but keeps its value between consecutive calls to discharge.

	In order for e to become admissible the other end-point say v has to push flow
Lemma 11	to u (so that the edge (u, v) re-appears
If $v = \text{null}$ in Line 3, then there is no	in the residual graph). For this the label
outgoing admissible edge from u .	of v needs to be larger than the label of
	u. Then in order to make (u, v) admissible the label of u has to increase.
Proof.	
While pushing from u the current	-neighbour pointer is only
advanced if the current edge is no	ot admissible.
The only thing that could make the theorem is a second	ie edge admissible again
would be a relabel at <i>u</i> .	
If we reach the end of the list (v =	= null) all edges are not
admissible.	
This shows that $discharge(u)$ is correct	ct, and that we can
perform a relabel in Line 4.	
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