# Part V

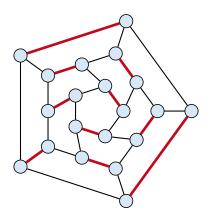
# Matchings



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## Matching

- lnput: undirected graph G = (V, E).
- $M \subseteq E$  is a matching if each node appears in at most one edge in M.
- Maximum Matching: find a matching of maximum cardinality



## **16 Bipartite Matching via Flows**

### Which flow algorithm to use?

- Generic augmenting path:  $\mathcal{O}(m \operatorname{val}(f^*)) = \mathcal{O}(mn)$ .
- Capacity scaling:  $\mathcal{O}(m^2 \log C) = \mathcal{O}(m^2)$ .
- Shortest augmenting path:  $\mathcal{O}(mn^2)$ .

For unit capacity simple graphs shortest augmenting path can be implemented in time  $\mathcal{O}(m\sqrt{n})$ .



### Definitions.

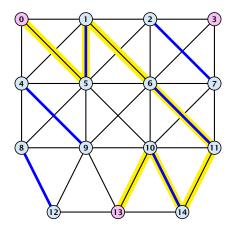
- Given a matching M in a graph G, a vertex that is not incident to any edge of M is called a free vertex w.r.t. M.
- ▶ For a matching *M* a path *P* in *G* is called an alternating path if edges in *M* alternate with edges not in *M*.
- An alternating path is called an augmenting path for matching *M* if it ends at distinct free vertices.

#### Theorem 1

A matching M is a maximum matching if and only if there is no augmenting path w. r. t. M.



## **Augmenting Paths in Action**

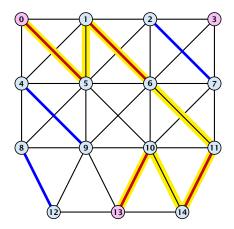




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## **Augmenting Paths in Action**





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Proof.

- ⇒ If *M* is maximum there is no augmenting path *P*, because we could switch matching and non-matching edges along *P*. This gives matching  $M' = M \oplus P$  with larger cardinality.
- $\leftarrow Suppose there is a matching M' with larger cardinality. Consider the graph H with edge-set M' \oplus M (i.e., only edges that are in either M or M' but not in both).$

Each vertex can be incident to at most two edges (one from M and one from M'). Hence, the connected components are alternating cycles or alternating path.

As |M'| > |M| there is one connected component that is a path P for which both endpoints are incident to edges from M'. P is an alternating path.



#### Algorithmic idea:

As long as you find an augmenting path augment your matching using this path. When you arrive at a matching for which no augmenting path exists you have a maximum matching.

#### Theorem 2

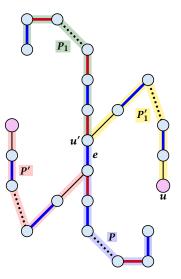
Let G be a graph, M a matching in G, and let u be a free vertex w.r.t. M. Further let P denote an augmenting path w.r.t. M and let  $M' = M \oplus P$  denote the matching resulting from augmenting M with P. If there was no augmenting path starting at u in M then there is no augmenting path starting at u in M'.

The above theorem allows for an easier implementation of an augmenting path algorithm. Once we checked for augmenting paths starting from u we don't have to check for such paths in future rounds.



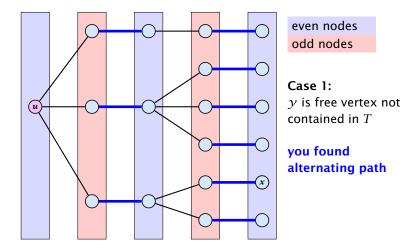
### Proof

- Assume there is an augmenting path P' w.r.t. M' starting at u.
- If P' and P are node-disjoint, P' is also augmenting path w.r.t. M (£).
- Let u' be the first node on P' that is in P, and let e be the matching edge from M' incident to u'.
- u' splits P into two parts one of which does not contain e. Call this part P<sub>1</sub>. Denote the sub-path of P' from u to u' with P'<sub>1</sub>.
- $P_1 \circ P'_1$  is augmenting path in M (2).





#### Construct an alternating tree.

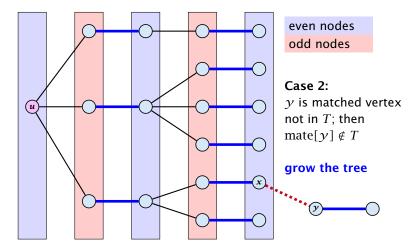




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#### Construct an alternating tree.

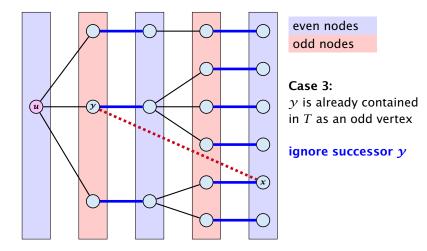




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#### Construct an alternating tree.

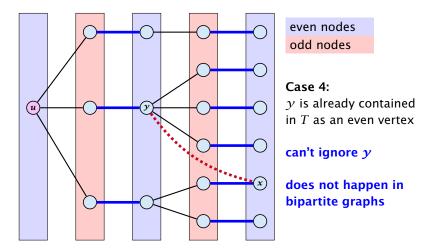




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#### Construct an alternating tree.





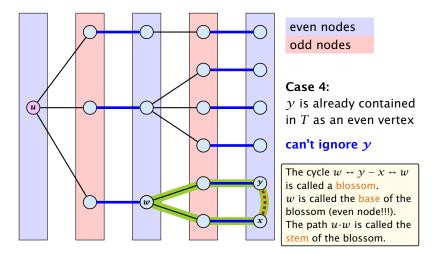
17 Augmenting Paths for Matchings

11. Apr. 2018 516/551 Algorithm 24 BiMatch(G, match)

```
1: for x \in V do mate[x] \leftarrow 0;
2: r \leftarrow 0; free \leftarrow n;
 3: while free \geq 1 and r < n do
4: r \leftarrow r + 1
 5: if mate[r] = 0 then
           for i = 1 to n do parent[i'] \leftarrow 0
6:
 7:
           Q \leftarrow \emptyset; Q. append(r); aug \leftarrow false;
8:
        while aug = false and Q \neq \emptyset do
               x \leftarrow Q.dequeue();
9:
10:
               for \gamma \in A_{\gamma} do
11:
                   if mate[\gamma] = 0 then
12:
                       augm(mate, parent, y);
13:
                       aug \leftarrow true;
14:
                       free \leftarrow free -1;
15:
                   else
16:
                       if parent[y] = 0 then
17:
                           parent[v] \leftarrow x;
                           Q.enqueue(mate[y]);
18:
```

The lecture slides contain a step by step  $G = (S \cup S', E)$  $S = \{1, ..., n\}$  $S' = \{1', ..., n'\}$ 

Construct an alternating tree.





18 Maximum Matching in General Graphs

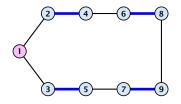
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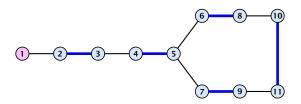
#### **Definition 3**

A flower in a graph G = (V, E) w.r.t. a matching M and a (free) root node r, is a subgraph with two components:

- A stem is an even length alternating path that starts at the root node *r* and terminates at some node *w*. We permit the possibility that *r* = *w* (empty stem).
- A blossom is an odd length alternating cycle that starts and terminates at the terminal node w of a stem and has no other node in common with the stem. w is called the base of the blossom.









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#### **Properties:**

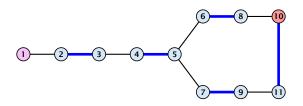
- 1. A stem spans  $2\ell + 1$  nodes and contains  $\ell$  matched edges for some integer  $\ell \ge 0$ .
- **2.** A blossom spans 2k + 1 nodes and contains k matched edges for some integer  $k \ge 1$ . The matched edges match all nodes of the blossom except the base.
- **3.** The base of a blossom is an even node (if the stem is part of an alternating tree starting at *r*).



#### **Properties:**

- 4. Every node x in the blossom (except its base) is reachable from the root (or from the base of the blossom) through two distinct alternating paths; one with even and one with odd length.
- 5. The even alternating path to x terminates with a matched edge and the odd path with an unmatched edge.







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## **Shrinking Blossoms**

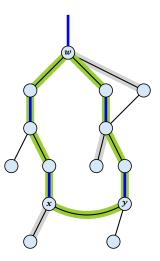
When during the alternating tree construction we discover a blossom B we replace the graph G by G' = G/B, which is obtained from G by contracting the blossom B.

- Delete all vertices in B (and its incident edges) from G.
- Add a new (pseudo-)vertex b. The new vertex b is connected to all vertices in V \ B that had at least one edge to a vertex from B.



## **Shrinking Blossoms**

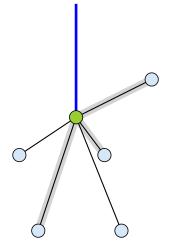
- Edges of T that connect a node u not in B to a node in B become tree edges in T' connecting u to b.
- Matching edges (there is at most one) that connect a node u not in B to a node in B become matching edges in M'.
- Nodes that are connected in G to at least one node in B become connected to b in G'.





## **Shrinking Blossoms**

- Edges of T that connect a node u not in B to a node in B become tree edges in T' connecting u to b.
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- Nodes that are connected in G to at least one node in B become connected to b in G'.





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### **Example: Blossom Algorithm**

Animation of Blossom Shrinking algorithm is only available in the lecture version of the slides.



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Assume that in *G* we have a flower w.r.t. matching *M*. Let *r* be the root, *B* the blossom, and *w* the base. Let graph G' = G/B with pseudonode *b*. Let *M'* be the matching in the contracted graph.

#### Lemma 4

If G' contains an augmenting path P' starting at r (or the pseudo-node containing r) w.r.t. the matching M' then G contains an augmenting path starting at r w.r.t. matching M.



18 Maximum Matching in General Graphs

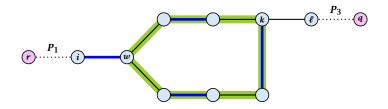
Proof.

If P' does not contain b it is also an augmenting path in G.

#### Case 1: non-empty stem

Next suppose that the stem is non-empty.







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- ► After the expansion ℓ must be incident to some node in the blossom. Let this node be k.
- If  $k \neq w$  there is an alternating path  $P_2$  from w to k that ends in a matching edge.
- ▶  $P_1 \circ (i, w) \circ P_2 \circ (k, \ell) \circ P_3$  is an alternating path.
- ▶ If k = w then  $P_1 \circ (i, w) \circ (w, \ell) \circ P_3$  is an alternating path.

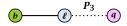


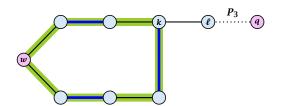
#### Proof.

#### Case 2: empty stem

If the stem is empty then after expanding the blossom,

w = r.





• The path  $r \circ P_2 \circ (k, \ell) \circ P_3$  is an alternating path.



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#### Lemma 5

If G contains an augmenting path P from r to q w.r.t. matching M then G' contains an augmenting path from r (or the pseudo-node containing r) to q w.r.t. M'.



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#### Proof.

- If P does not contain a node from B there is nothing to prove.
- We can assume that *r* and *q* are the only free nodes in *G*.

#### Case 1: empty stem

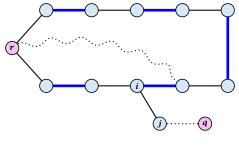
Let i be the last node on the path P that is part of the blossom.

P is of the form  $P_1 \circ (i, j) \circ P_2$ , for some node j and (i, j) is unmatched.

 $(b, j) \circ P_2$  is an augmenting path in the contracted network.



Illustration for Case 1:







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#### Case 2: non-empty stem

Let  $P_3$  be alternating path from r to w; this exists because r and w are root and base of a blossom. Define  $M_+ = M \oplus P_3$ .

In  $M_+$ , r is matched and w is unmatched.

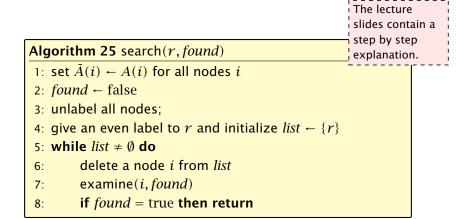
*G* must contain an augmenting path w.r.t. matching  $M_+$ , since *M* and  $M_+$  have same cardinality.

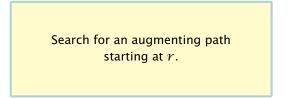
This path must go between w and q as these are the only unmatched vertices w.r.t.  $M_+$ .

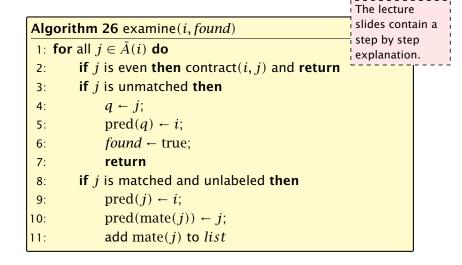
For  $M'_+$  the blossom has an empty stem. Case 1 applies.

G' has an augmenting path w.r.t.  $M'_+$ . It must also have an augmenting path w.r.t. M', as both matchings have the same cardinality.

This path must go between r and q.







Examine the neighbours of a node *i* 

#### Algorithm 27 contract(*i*, *j*)

- 1: trace pred-indices of i and j to identify a blossom B
- 2: create new node b and set  $\bar{A}(b) \leftarrow \bigcup_{x \in B} \bar{A}(x)$
- 3: label *b* even and add to *list*
- 4: update  $\bar{A}(j) \leftarrow \bar{A}(j) \cup \{b\}$  for each  $j \in \bar{A}(b)$
- 5: form a circular double linked list of nodes in B
- 6: delete nodes in *B* from the graph

Contract blossom identified by nodes i and j



Algorithm 27 contract(*i*, *j*)

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Get all nodes of the blossom.

Time:  $\mathcal{O}(m)$ 



- 1: trace pred-indices of i and j to identify a blossom B
- 2: create new node *b* and set  $\bar{A}(b) \leftarrow \bigcup_{x \in B} \bar{A}(x)$
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- 6: delete nodes in *B* from the graph

Identify all neighbours of *b*.

Time:  $\mathcal{O}(m)$  (how?)



- 1: trace pred-indices of i and j to identify a blossom B
- 2: create new node b and set  $\bar{A}(b) \leftarrow \bigcup_{x \in B} \bar{A}(x)$
- 3: label *b* even and add to *list*
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- 6: delete nodes in *B* from the graph

*b* will be an even node, and it has unexamined neighbours.



- 1: trace pred-indices of i and j to identify a blossom B
- 2: create new node b and set  $\bar{A}(b) \leftarrow \bigcup_{x \in B} \bar{A}(x)$
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Every node that was adjacent to a node in *B* is now adjacent to *b* 



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- 6: delete nodes in *B* from the graph

Only for making a blossom expansion easier.



- 1: trace pred-indices of i and j to identify a blossom B
- 2: create new node b and set  $\bar{A}(b) \leftarrow \bigcup_{x \in B} \bar{A}(x)$
- 3: label *b* even and add to *list*
- 4: update  $\bar{A}(j) \leftarrow \bar{A}(j) \cup \{b\}$  for each  $j \in \bar{A}(b)$
- 5: form a circular double linked list of nodes in B

6: delete nodes in *B* from the graph

Only delete links from nodes not in *B* to *B*.

When expanding the blossom again we can recreate these links in time  $\mathcal{O}(m)$ .



# Analysis

- A contraction operation can be performed in time O(m).
   Note, that any graph created will have at most m edges.
- The time between two contraction-operation is basically a BFS/DFS on a graph. Hence takes time O(m).
- There are at most n contractions as each contraction reduces the number of vertices.
- The expansion can trivially be done in the same time as needed for all contractions.
- An augmentation requires time O(n). There are at most n of them.
- In total the running time is at most

$$n \cdot (\mathcal{O}(mn) + \mathcal{O}(n)) = \mathcal{O}(mn^2)$$
.

### **Example: Blossom Algorithm**

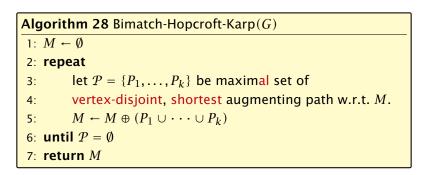
Animation of Blossom Shrinking algorithm is only available in the lecture version of the slides.



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### A Fast Matching Algorithm



We call one iteration of the repeat-loop a phase of the algorithm.



### Lemma 6

Given a matching M and a maximal matching  $M^*$  there exist  $|M^*| - |M|$  vertex-disjoint augmenting path w.r.t. M.

### Proof:

- Similar to the proof that a matching is optimal iff it does not contain an augmenting path.
- Consider the graph G = (V, M ⊕ M\*), and mark edges in this graph blue if they are in M and red if they are in M\*.
- The connected components of *G* are cycles and paths.
- ► The graph contains k ≝ |M\*| |M| more red edges than blue edges.
- Hence, there are at least k components that form a path starting and ending with a red edge. These are augmenting paths w.r.t. M.



- Let  $P_1, \ldots, P_k$  be a maximal collection of vertex-disjoint, shortest augmenting paths w.r.t. *M* (let  $\ell = |P_i|$ ).
- $M' \stackrel{\text{\tiny def}}{=} M \oplus (P_1 \cup \cdots \cup P_k) = M \oplus P_1 \oplus \cdots \oplus P_k.$
- Let P be an augmenting path in M'.

#### Lemma 7

The set  $A \cong M \oplus (M' \oplus P) = (P_1 \cup \cdots \cup P_k) \oplus P$  contains at least  $(k+1)\ell$  edges.



### Proof.

- The set describes exactly the symmetric difference between matchings M and  $M' \oplus P$ .
- ► Hence, the set contains at least k + 1 vertex-disjoint augmenting paths w.r.t. M as |M'| = |M| + k + 1.
- Each of these paths is of length at least  $\ell$ .



### Lemma 8

*P* is of length at least  $\ell + 1$ . This shows that the length of a shortest augmenting path increases between two phases of the Hopcroft-Karp algorithm.

### Proof.

- ► If P does not intersect any of the P<sub>1</sub>,..., P<sub>k</sub>, this follows from the maximality of the set {P<sub>1</sub>,..., P<sub>k</sub>}.
- Otherwise, at least one edge from P coincides with an edge from paths {P<sub>1</sub>,...,P<sub>k</sub>}.
- This edge is not contained in *A*.
- Hence,  $|A| \le k\ell + |P| 1$ .
- ► The lower bound on |A| gives  $(k+1)\ell \le |A| \le k\ell + |P| 1$ , and hence  $|P| \ge \ell + 1$ .

If the shortest augmenting path w.r.t. a matching M has  $\ell$  edges then the cardinality of the maximum matching is of size at most  $|M| + \frac{|V|}{\ell+1}$ .

#### Proof.

The symmetric difference between M and  $M^*$  contains  $|M^*| - |M|$  vertex-disjoint augmenting paths. Each of these paths contains at least  $\ell + 1$  vertices. Hence, there can be at most  $\frac{|V|}{\ell+1}$  of them.



### Lemma 9

The Hopcroft-Karp algorithm requires at most  $2\sqrt{|V|}$  phases.

### Proof.

- ▶ After iteration  $\lfloor \sqrt{|V|} \rfloor$  the length of a shortest augmenting path must be at least  $\lfloor \sqrt{|V|} \rfloor + 1 \ge \sqrt{|V|}$ .
- ► Hence, there can be at most  $|V|/(\sqrt{|V|} + 1) \le \sqrt{|V|}$  additional augmentations.



#### Lemma 10

One phase of the Hopcroft-Karp algorithm can be implemented in time O(m).

construct a "level graph" G':

- construct Level 0 that includes all free vertices on left side L
- construct Level 1 containing all neighbors of Level 0
- construct Level 2 containing matching neighbors of Level 1
- construct Level 3 containing all neighbors of Level 2
- ...

stop when a level (apart from Level 0) contains a free vertex can be done in time O(m) by a modified BFS



- a shortest augmenting path must go from Level 0 to the last layer constructed
- it can only use edges between layers
- construct a maximal set of vertex disjoint augmenting path connecting the layers
- for this, go forward until you either reach a free vertex or you reach a "dead end" v
- if you reach a free vertex delete the augmenting path and all incident edges from the graph
- if you reach a dead end backtrack and delete v together with its incident edges



See lecture versions of the slides.

### **Analysis: Shortest Augmenting Path for Flows**

#### cost for searches during a phase is $\mathcal{O}(mn)$

- a search (successful or unsuccessful) takes time  $\mathcal{O}(n)$
- a search deletes at least one edge from the level graph

#### there are at most *n* phases

Time:  $\mathcal{O}(mn^2)$ .



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### Analysis for Unit-capacity Simple Networks

#### cost for searches during a phase is $\mathcal{O}(m)$

an edge/vertex is traversed at most twice

#### need at most $\mathcal{O}(\sqrt{n})$ phases

- after  $\sqrt{n}$  phases there is a cut of size at most  $\sqrt{n}$  in the residual graph
- hence at most  $\sqrt{n}$  additional augmentations required

Time:  $\mathcal{O}(m\sqrt{n})$ .

